

SCHÉMAS D'ORDRE ÉLEVÉS POUR LA SIMULATION DE LA TURBULENCE ET DES INSTABILITÉS DANS LES PLASMAS DE BORD DE TOKAMAKS

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Colloque de prospective de la FR-FCM, jeudi 24 novembre.

- ▶ Development of **advanced numerical methods**
 - ◆ high order schemes
 - ⇒ well adapted to the simulation of instabilities (or turbulence).
 - ◆ on unstructured meshes
 - ⇒ able to handle complex geometries.

- ▶ Simulation of edge plasma in tokamaks:
 - ◆ in toroidal geometry.
 - ◆ multi-fluid full braginskii model coupled with Maxwell equations
 - ↪ bi-fluid full Braginskii model with the electrostatic assumption.
 - ↪ (reduced) MHD model.

- ▶ Development of computational tools

FINITE VOLUME METHODS FOR MHD MODELS

E. Estibals (PhD), H. Guillard, A. Sangam

- ▶ Projection at each time step on a rotated gradient field
 - ◆ strict respect of the divergence free constraint on the magnetic field
 - ◆ extremely cheap

\mathcal{C}^1 FINITE ELEMENT METHODS FOR MHD MODELS

J. Costa (PhD), H. Guillard, B. Nkonga

- ▶ Introduction of a vector potential
 - ◆ efficient way to deal with divergence free constraint on the magnetic field
 - ◆ introduce of higher order derivatives terms
- ▶ Two strategies
 - ◆ quadrangular cubic Hermite Bezier basis
 - ◆ 2D triangular Powell Sabin FE

\mathcal{C}^0 FINITE ELEMENT METHODS FOR FULL BRAGINSKII MODELS

S. Minjeaud, R. Pasquetti

- ▶ Spectral Element Method

- ▶ Mixing of finite elements and spectral methods
 - ◆ Handle complex geometries,
 - ◆ Well adapted to non-linear and anisotropic PDEs,
 - ◆ Spectrally accurate wrt the polynomial approx. degree (for smooth pb).

- ▶ Based on a weak formulation of the PDEs and a Galerkin approx.
 - ◆ Reference (master) element: $Q_{ref} = [-1, 1] \times [-1, 1]$.
 - ◆ P_N approximation on Q_{ref} .
 - ◆ Interpolation / quadrature points : tensorial product of the GLL points.
 - ◆ Basis functions: Lagrange polynomials based on the GLL points.
 - ◆ Quadratures exact in P_{2N-1} .
 - ◆ Isoparametric mappings, $\mathbf{f}_Q : Q_{ref} \rightarrow Q$.

- ▶ Geometry:
 - ◆ 3D geometry with a periodic direction (toroidal domains)
 - ◆ high flexibility with the poloidal geometry (unstructured meshes)
- ▶ Numerical schemes: high order methods
 - ◆ Fourier approx. in the toroidal direction (uniform mesh)
 - ◆ SEM in poloidal planes (2D unstructured quadrangular mesh)
- ▶ Linear Algebra:
 - ◆ native matrix free solver (cg or bicgstab) with jacobi precondition.,
 - ◆ coupling with PETSC library (large choice of precondition.)
- ▶ a Fortran-MPI implementation:
 - ◆ domain decomposition of the poloidal plane,
 - ◆ distribution of the poloidal planes and Fourier modes,
 - ◆ Almost transparent for the user.
- ▶ Model:
 - ◆ provides high level routines to assemble the different terms,
 - ◆ Spectral Vanishing Viscosity stabilization technique.

MODELING HYPOTHESIS

- ◆ A two-fluid ion-electron modeling,
- ◆ Conservation of density, momentum and energy + Braginskii closures,
- ◆ Electric neutrality: $\sum_s n_s e_s = 0$ (n_s : density, e_s : charge),
- ◆ \mathbf{B} is fixed and axisymmetric,
- ◆ \mathbf{E} is electrostatic: $\mathbf{E} = -\nabla U$,
- ◆ State laws $p_s = n_s T_s$ and $\varepsilon_s = p_s / (\gamma - 1)$.

THE FULL PDES SYSTEMS

▶ $\rho_s = n_s m_s$, $\rho = \sum_s \rho_s$ and $\mathbf{q}_s = \rho_s \mathbf{u}_s$.

▶ $w_s = e_s / m_s$ and $\alpha_s = w_s \rho_s / \rho$

$$\partial_t \rho + \nabla \cdot (\mathbf{q}_i + \mathbf{q}_e) = 0$$

$$\partial_t \mathbf{q}_s + \nabla \cdot (\mathbf{q}_s \mathbf{u}_s + p_s \mathbf{I} + \mathbf{\Pi}_s) = -\alpha_s \rho \nabla U + w_s \mathbf{q}_s \wedge \mathbf{B} + \mathbf{R}_s$$

$$\nabla \cdot (w_i \mathbf{q}_i + w_e \mathbf{q}_e) = 0$$

$$\partial_t \varepsilon_s + \nabla \cdot (\varepsilon_s \mathbf{u}_s + \boldsymbol{\varphi}_s) = -p_s \nabla \cdot \mathbf{u}_s - \mathbf{\Pi}_s : \nabla \mathbf{u}_s + Q_s$$

↪ 10 scalar PDEs,

↪ 10 unknown scalar fields: ρ (1), \mathbf{q}_s (6), ε_s (2), U (1)

STRANG SPLITTING

- System I: explicit treatment (ERK scheme) and subtime cycling

$$\partial_t \rho + \nabla \cdot (\mathbf{q}_i + \mathbf{q}_e) = 0$$

$$\partial_t \mathbf{q}_s + \nabla \cdot (\mathbf{q}_s \mathbf{u}_s + p_s \mathbf{I} + \Pi_s) = \mathbf{R}_s$$

$$\partial_t p_s + \nabla \cdot (p_s \mathbf{u}_s + (\gamma - 1) \boldsymbol{\varphi}_s) = (\gamma - 1)(-p_s \nabla \cdot \mathbf{u}_s - \Pi_s : \nabla \mathbf{u}_s + Q_s)$$

- System II: implicit treatment (DIRK scheme)

$$\partial_t \mathbf{q}_s = -\alpha_s \rho \nabla U + w_s \mathbf{q}_s \wedge \mathbf{B}$$

$$\nabla \cdot (w_i \mathbf{q}_i + w_e \mathbf{q}_e) = 0$$

EQUATION FOR THE POTENTIAL

- Elimination of the \mathbf{q}_s in System II

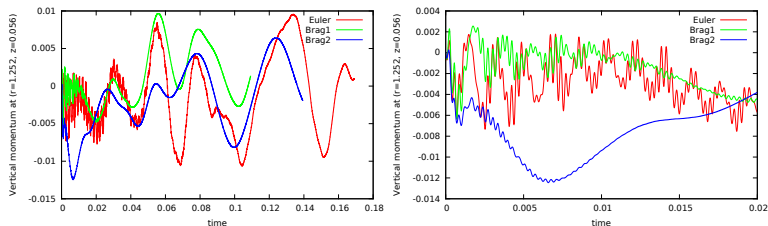
$$\nabla \cdot A \nabla U = \sum_s w_s \nabla \cdot A_s \tilde{\mathbf{q}}_s$$

where $\tilde{\mathbf{q}}_s$ is the previous ERK estimate of \mathbf{q}_s and

- ◆ A is definite positive
- ◆ A is an anisotropic tensor, the anisotropy ratio depends on δt

	$\delta t = \omega_{ci}$	$\delta t = \omega_{ce}$
A_{\perp}/A_{\parallel}	$5.01 \cdot 10^{-5}$	$9.24 \cdot 10^{-2}$

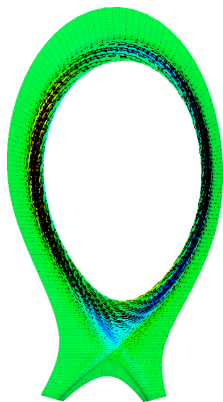
► Numerical experiments



Vertical momentum at (1.25, 0.056) for the Euler and for two Braginskii computations

- Observation: **dominant frequencies** $\approx 3000, 40$.
- Link with cyclotronic frequencies ?
 - ◆ At this point, in dimensionless form $B = 2375$,
 - ◆ $f_{ic} = Be/(2\pi m_i) \approx 378$ and $f_{ec} = Be/(2\pi m_e) = 100f_{ic} \approx 37800$

$$Be/(2\pi\sqrt{m_e m_i}) \approx 3780 \rightsquigarrow \text{same order of magnitude...}$$



current

- ▶ Preliminary computations :
 - ◆ 31194 grid points (3000 cells with $n = 3$).
 - ◆ Computations up to few micro-seconds.
 - ◆ Heavy electron assumption : $m_e = m_i/100$
 - ◆ Parallel transport coefficients divided by 10

- ▶ Difficulties :
 - ◆ Bohm boundary conditions
 - ◆ Slip BC at the center of the domain ?

S. Minjeaud, R. Pasquetti, JCP, 2016

SEM SCHEME FOR A REDUCED MHD MODEL

H. Guillard, S. Minjeaud, R. Pasquetti

$$\begin{aligned}\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla \lambda &= (\mathbf{b} \cdot \nabla) \mathbf{b} + \partial_z \mathbf{b}, \\ \partial_t \mathbf{b} + (\mathbf{u} \cdot \nabla) \mathbf{b} &= (\mathbf{b} \cdot \nabla) \mathbf{u} + \partial_z \mathbf{u}, \\ \nabla \cdot \mathbf{u} &= 0.\end{aligned}$$

H. Guillard, INRIA Research report, 15.

- ▶ Comparison with other codes.
- ▶ Cross validation of the numerical strategies.
- ▶ Comparison accuracy/cost.